

NAVIPAC OUTPUT TO IMCA TELEMETRY SYSTEM

Last update: 31/03/2020 Version: 4.2



1 General guidelines

This document gives a short description on how to set up NaviPac to output data to an IMCA system.

Go to the NaviPac **Project settings**, option **Survey parameters** to specify e.g. the **Project** name, **Client** initials, **Area** and enter the two character for **IMCA Id**:

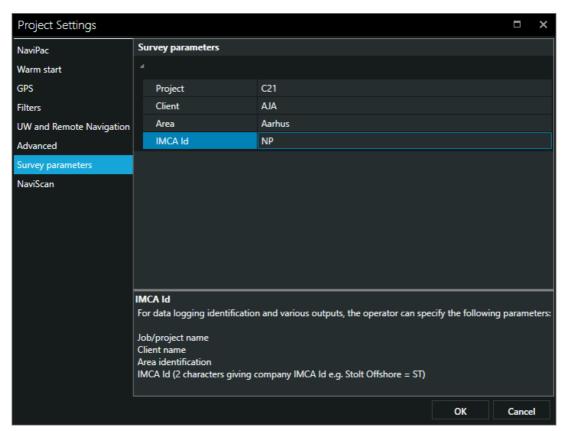


Figure 1 Survey parameters

Add a **Data to ext. nav. System output** on the vehicle/s that you wish to send an IMCA output from, e.g. the main vessel and an ROV.





Figure 2 Data Output: Data to ext. nav. system

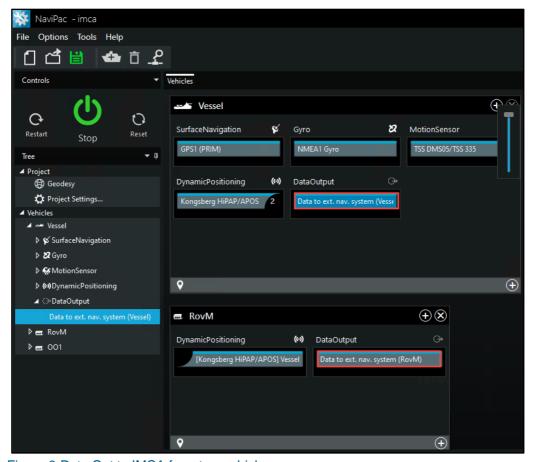


Figure 3 Data Out to IMCA from two vehicles



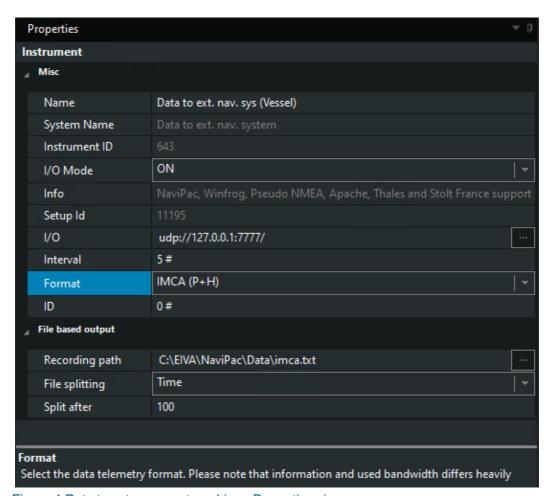


Figure 4 Data to ext. nav. system driver: Properties view

I/O

Define a IMCA data output for each vehicle, e.g. vessel, Rov1 and OO1. They will be combined to one when starting NaviPac.

Interval

Select a reasonable data rate (5.00 will result in 5 seconds between each output)

• Format

Select the format to IMCA (P+H)

• IL

Select identification number – must be used for id of data at receiving point

Recording path

The default path is C:\EIVA\NaviPac\Data\

File splitting

Can be set to split by Time in minutes, or File Size in KB

The output will hereafter act as any ordinary output.



The data can be viewed in the Instrument Spy.

Enable the Instrument Spy from the NaviPac Online menu bar, alternatively activate it from NaviPac **Online / Options / Instrument Control. Select** Instrument monitor and control:

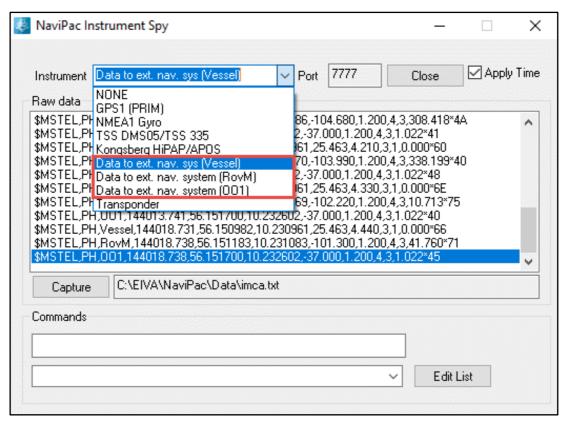


Figure 5 NaviPac Online: Instrument Spy



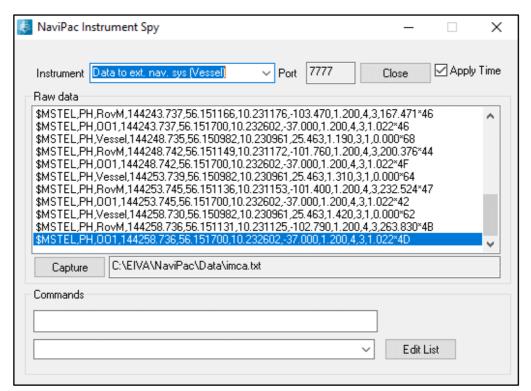


Figure 6 NaviPac Instrument Spy with three IMCA outputs

In this example the data outputs from the NaviPac vehicles.gives you one update per selected vehicle/Object ID:

*** EIVA a/s - NaviPac InsMon Capture:Data to ext. nav. system (Vessel) \$MSTEL,PH,Vessel,000924.993,56.158571,10.223948,37.400,5.130,3,1,0.000*63 \$MSTEL,PH,RovM,000925.013,56.158773,10.224147,-104.700,1.200,4,3,0.000*41 \$MSTEL,PH,O01,000925.013,56.159200,10.225605,-37.000,1.200,4,3,0.000*3F \$MSTEL,PH,Vessel,000925.995,56.158571,10.223948,37.400,5.150,3,1,0.000*62 \$MSTEL,PH,RovM,000926.014,56.158770,10.224151,-104.670,1.200,4,3,0.000*47 \$MSTEL,PH,O01,000926.014,56.159200,10.225605,-37.000,1.200,4,3,0.000*3B



The strings are formatted as:

\$<IMCA Id>TEL,PH,<Name>,<hhmmss.ss>,<Latitude>,<Longitude>,<height>,<std dev>,<source>,<status>,<true heading><cr><lf>

Where

IMCA Id:

Gives the entered 2 character Id

• Name:

Gives the vehicle name as selected/entered in setup

Hhmmss.ss:

Time stamp in UTC

• Latitude:

Position latitude in WGS84

Longitude:

Position longitude in WGS84

Height:

Height (positive) or depth (negative) of the vehicle

Std dev:

Position accuracy indicator. Gives position DOP

• Source:

Position source

• GPS/DGPS/RTK (1-3)

Vessel position or offsets - GPS status

USBL (4)

Dynamic positioned objects

• Status

Status of positioning

RAW (1)

Raw positioning data - eg. Vessel reference positions

• FILTERED (2)

Filtered position -eg. Kalman filtered position

DERIVED (3)

Calculated position (offset or dynamic offset)

True heading

Gives the true heading of the vehicle

Note, the **Commands** option in the **Instrument Spy** are used for reading telemetry data in IMCA format, described in the manual, **Reading telemetry data in IMCAformat.pdf**. This is not required for the IMCA output.

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